

HG 660

Hollow Shaft Incremental Encoder

Features

Through or blind hollow shaft
incremental encoder

Resolutions up to 10,000 ppr

AquadB with index marker
signal format

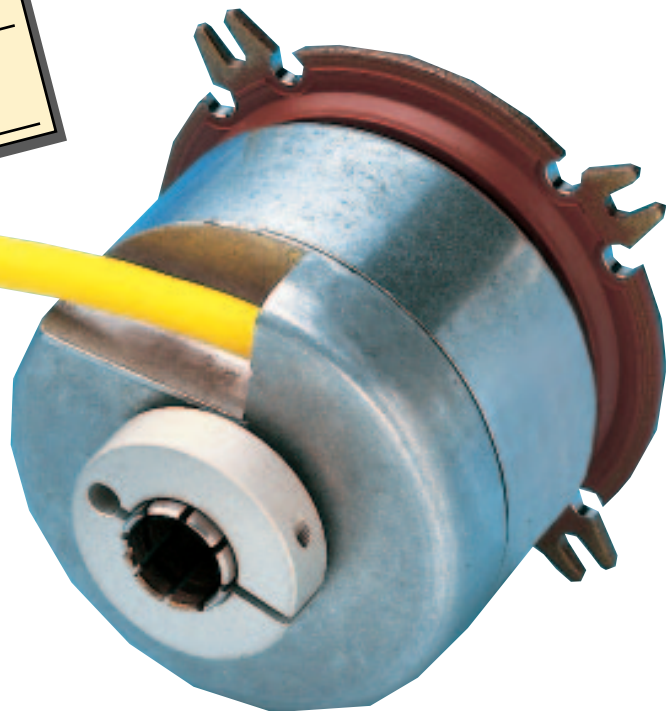
+5VDC Line Driver or 10-30
VDC push-pull output drivers

60 mm external diameter

Rugged die-cast aluminum
housing with IP65 protection

Hollow shaft diameters from 6
mm (.23") to 15 mm (.59")

Viton Flex Mount for improved
dynamic stability



Technical Data/Features according to DIN 32878

Number of pulses per revolution(Z) **RS 422 and Push-Pull:** 100, 250, 360, 500, 1000, 1024, 1250, 2000, 2048, 2500, 3000, **3600**, 4096, 5000
RS 422 only: 200, 720, 4000, 7200, 8192, 10000

Interfaces		RS 422, Push-pull outputs, 1Vp-p Sine/Cosine
Dimensions		See drawing (mm)
Mass		Approx. 0.3 kg
Moment of inertia of the rotor		45 gcm ²
Measurement step		90 / Z°
Reference signal	Number	1
	Position	90° electrical (gated with K1 and K2)
Error limit		45 / Z + 0.054 degrees
		45 / Z + 0.015 degrees
Measurement step deviation		45 / Z°
Max. output frequency	RS 422 Output	300 kHz (up to 5000 Resolution) 600 kHz (above 5000 Resolution)
	Push-pull Output	200kHz
Max operating speed		6000 rpm
Max. angular acceleration		5 x 10 ⁵ rad/s ²
Operating torque		0.2 Ncm
Starting torque		0.4 Ncm
Permissible movement of the drive element:	Radial movement	static ±0.1 mm dynamic ±0.05 mm
	Axial movement	static ±2 mm dynamic ±0.2 mm
Angular movement at right angles to the axis		static 34 x 10 ³ mm/mm dynamic 17 x 10 ³ mm/mm
Service life of bearings		3.6 x 10 ⁹ Revolutions
Design performance temperature range		-20 to +70 °C
Operating temperature range		-20 to +85 °C
Storage temperature range		-30 to +85 °C
Permissible relative humidity		90% (condensation not permissible)
EMC in accordance with EN 50082-2 and 50081-2		
Shock resistance to DIN IEC 68 Part 2 - 27 (assembled state)		30 / 11 g/ms
Vibration resistance to DIN IEC 68 Part 2 - 6 (assembled state)		20/10 to 150 g/Hz
Degree of protection to DIN VDE 0470 Part 1 (assembled state)		IP 65
Operating voltage range	RS 422	4 to 6 VDC or 10 to 30 VDC
	Push-pull	10 to 30 VDC
	Sine/Cosine	5 VDC
Operating current at no load	24 V	100 mA
	5 V	120 mA
Signal cable (power supply at no potential)	Diameter	6 mm
	Min. bending radius	30 mm
	Length	1.5 m

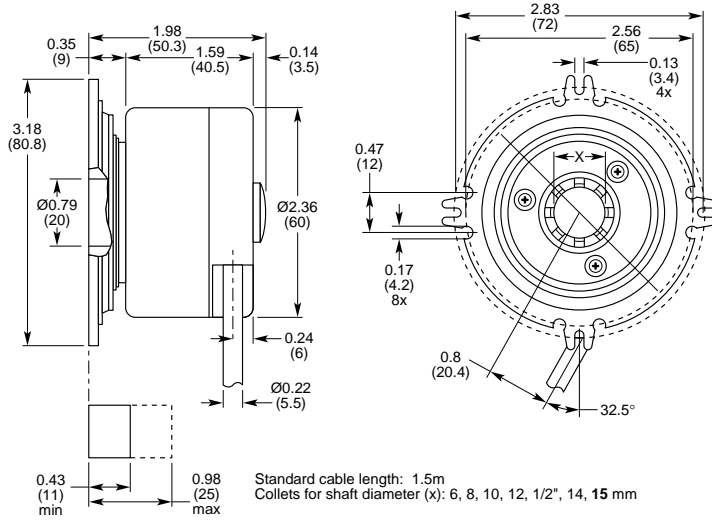
* Power supply is at no potential to housing, shield is at housing potential.

HG 660

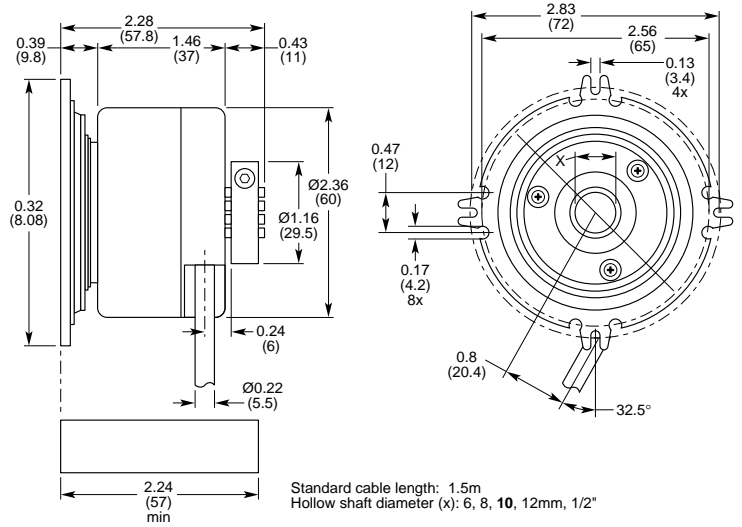


Dimensions (mm)

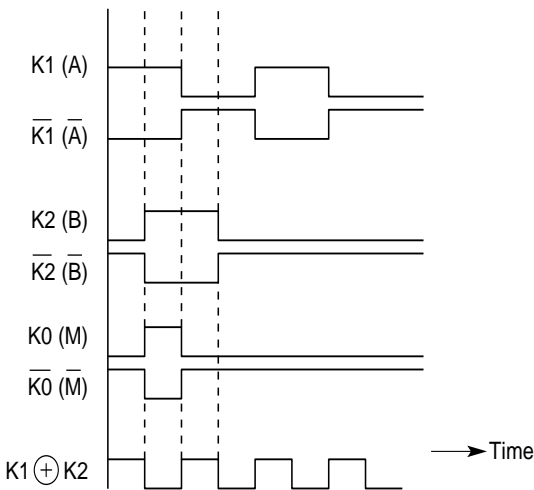
HG 660 AKR



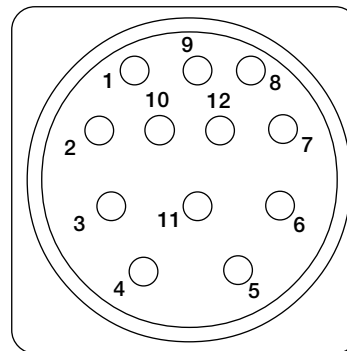
HG 660 DKR



Output Wave Forms



Pin Out of Receptacle Connector on Encoder



NOTES:

1. "Exclusive OR" of K1 (+) K2 provides four times increase in resolution. (not a direct output of the encoder)
2. K1 leads K2 for clockwise rotation when viewed from shaft end.

Electrical Connections

Pin	Wire Color	Signal 24 V push-pull	Signal 5 V RS 422	Explanation
1	black	N.C.	$\overline{K2}$	\overline{B} output
2	grey	N.C.	Sense +	Internal, connect to US (+Vs)
3	violet	K0	K0	M output
4	yellow	N.C.	$\overline{K0}$	\overline{M} output
5	white	K1	K1	A output
6	brown	N.C.	$\overline{K1}$	\overline{A} output
7	orange	N.C.	N.C.	Not connected
8	pink	K2	K2	B output
9	shield	shield	shield	Overall shield
10	blue	GND	GND	Earth connect of the encoder
11	green	GND	Sense -	Internally connected to GND
12	red	US (+Vs)	US (+Vs)	Encoder supply voltage (+Vs)

Note: NC = not connected, pins/wires with this designation should not be connected

Supply Voltage/Output Driver Chart

Supply Voltage	Output Driver	Identification Character
4 to 6 V	RS 422	F
10 to 30 V	RS 422	G
10 to 30 V	Push-Pull	6

How To Order

Hollow Shaft/Collet Chart

HG660 AKR Collets 6, 8, 10, 12, 1/2", 14, 15 mm
 HG 660 DKR Hollow Shaft Chart 6, 8, 10, 12 mm, 1/2"



Example for ordering

HG 660, DKR option, 4 to 6 V RS 422, hollow shaft 12 mm, 3600 pulses per revolution
 = **HG 660-DKR-3600-F, 12mm**