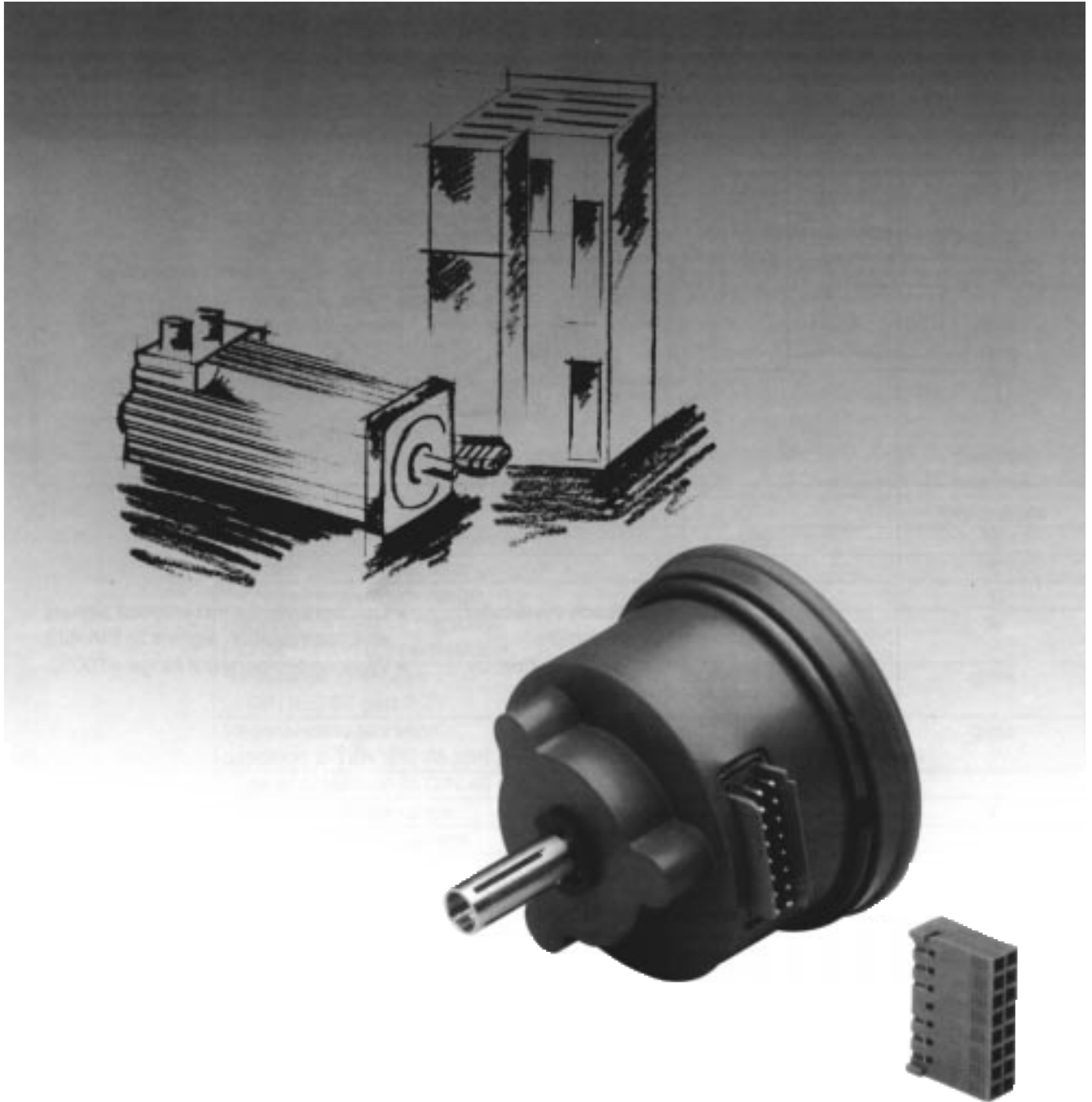


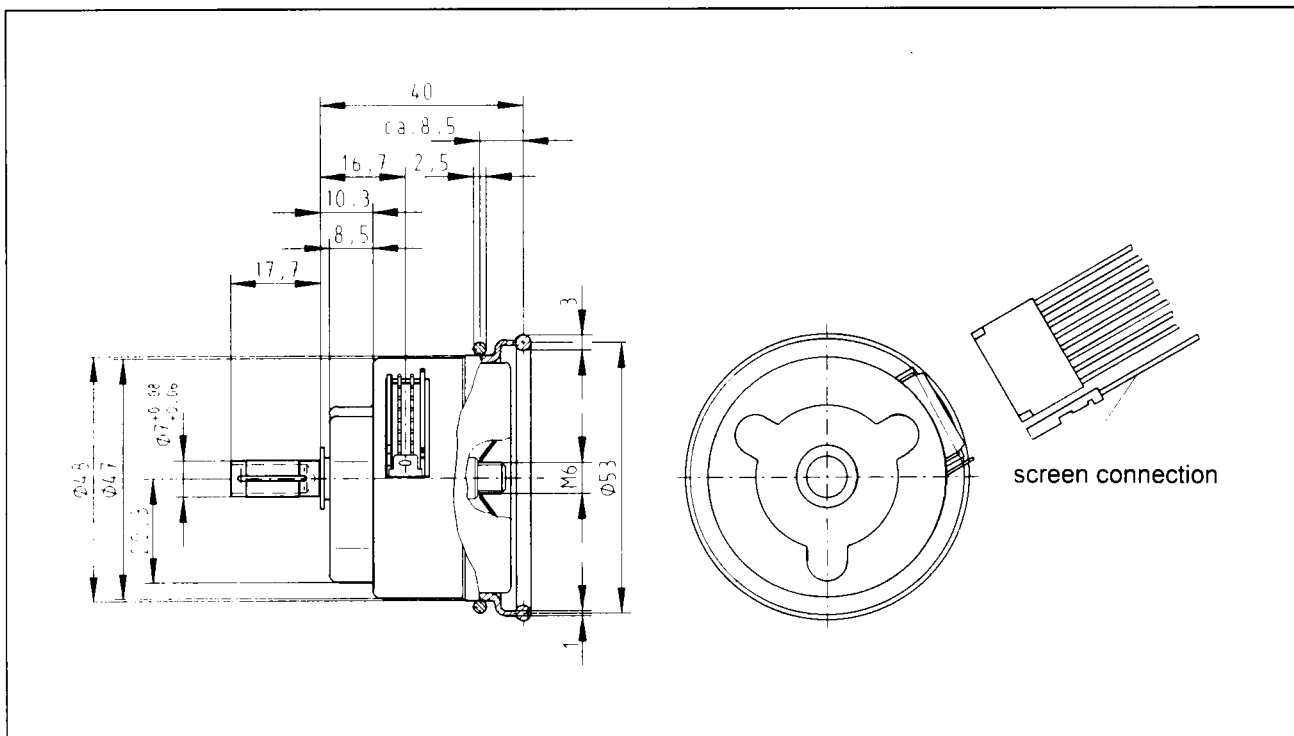


CDD 50 DiCoder Motor Feedback System



CDD 50

Dimensional drawing and Features



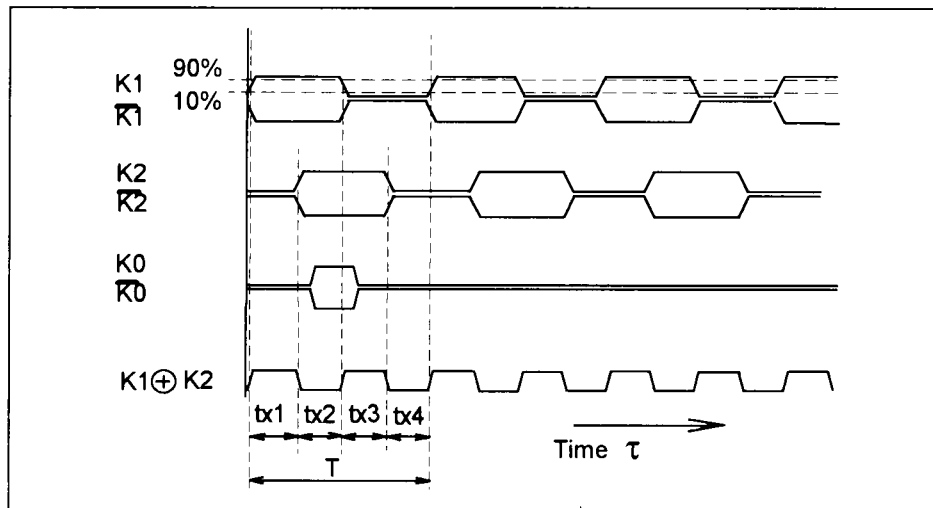
- DiCoder motor feedback system for installation in electric motors
- Two square-wave signals, offset by 90°, reference pulse and the respectively inverted signals
- Commutation signals
- Output driver for incremental signals and commutation signals to EIA 422
- Working temperature range +100°C

| | | Units | |
|---|--------------------|---|-------------------|
| Number of pulses (Z) per revolution | | 1024, 2048, 4096 | |
| Commutation signals | | 6pole (see diagram) other commutation on request | |
| Dimensions | | See dimensional drawing | |
| Mass | | 0.1 | kg |
| Moment of inertia of the rotor | | 10 | gcm ² |
| Measurement step | | 90/ number of pulses | Degrees |
| Reference signal | Number Position | 1 90° electric, logically linked to K1 and K2 | |
| Max. angular acceleration | | 300 | kHz |
| Max. operating speed | | 9000 | min ⁻¹ |
| Working speed | | 6000 | min ⁻¹ |
| Max. angular acceleration | | 0.2 x 10 ⁶ | 1/s ² |
| Operating torque | | 0.2 | Ncm |
| Starting torque | | 0,4 | Ncm |
| Permissible shaft movement | | | |
| - Radial movement | static | 1 | mm |
| | dynamic | 0.1 | mm |
| - Axial movement | static | 1.5 | mm |
| | dynamic | 1 | mm |
| - Angular movement | | | |
| perpendicular to axis of | static | 0.01 | mm/mm |
| rotation | dynamic | 0.005 | mm/mm |
| Bearing life | | 3.6 x 10 ⁹ | Revolutions |
| Working temperature range | | 0 +100 | °C |
| Operating temperature range | | -20 +125 | °C |
| Storage temperature range | | -40 +125 | °C |
| Permissible relative humidity (condensation not permissible) | | 90 | % |
| Resistance to shocks to DIN IEC 68 part 2-27 | | 100/10 | g/ms |
| Resistance to vibration condition to DIN IEC 68 part 2-6 | | 20/0 ... 2000 | g/Hz |
| Type of protection to DIN 40 050 | | IP 40 | |
| Operating voltage range | | 5 ±10% | V |
| No-load operating current | | 50 | mA |
| Information on interface: output driver | | To DIN 66 259 Part 3 and EIA Standard RS 422 | |
| Output signal train | | See pulse timing diagram | |
| Signal tolerance tx1 ... tx4 _{max} bei 300 kHz | | 1.5 x ¼ T | |

Pulse timing diagrams

Incremental tracks
At constant rotational speed,

viewed towards the input shaft and
clockwise rotation



By linking the two signals K1 and K2 whose periods $tx_1 \dots tx_4$ have different magnitudes, an output signal is produced.

The differences are determined:

1. by the mark/space ratio tolerance of the individual channels
2. by the tolerance in the 90° phase shift between K1 and K2

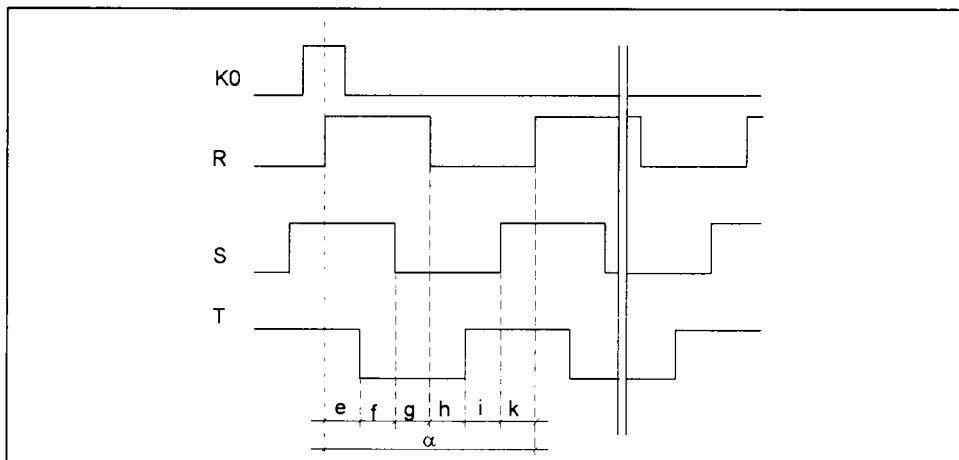
3. by the frequency

In the ideal case, the times $tx_1 \dots tx_4$ would in each case have to be 1/4 of the period T. The typical output frequency of the encoder is defined such that the maximum time tx is smaller than $1.5 \times T/4$.

Pulse timing diagram

For 6-pole commutation (3 pole pairs)

and 8-pole commutation (4pole pairs)



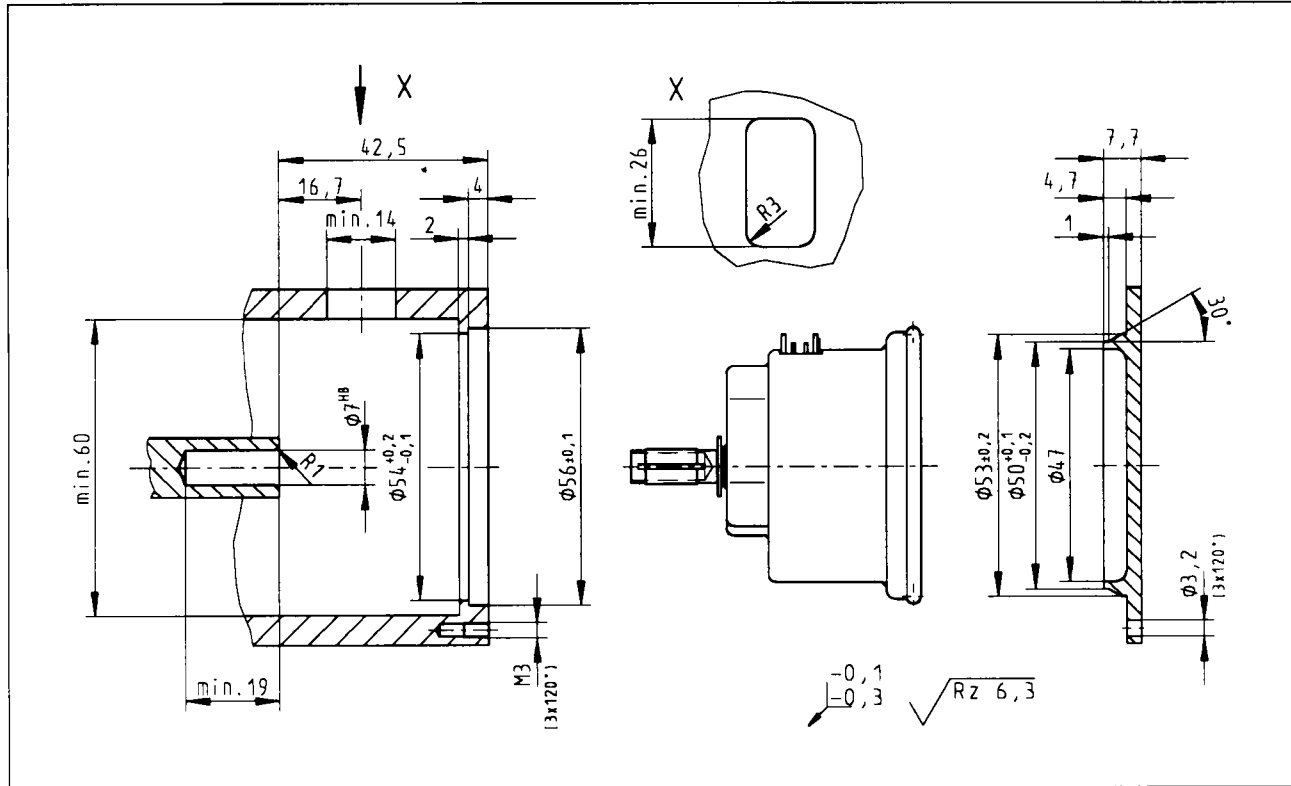
| Number of poles | e, f, g, h, i, k | α |
|-----------------|------------------|----------|
| 6 | 20° | 120° |
| 8 | 15° | 90° |

The angle values are mechanical degrees over one shaft revolution.

Flanc accuracy of the signals R, S, T $\pm 1^\circ$

CDD 50

Recommended installation



The removal of a fitting of the device should only be effected using the rear end of the encoder shaft.

Under no circumstances should you press against the encoder housing!

Refer to the Mounting Instructions!

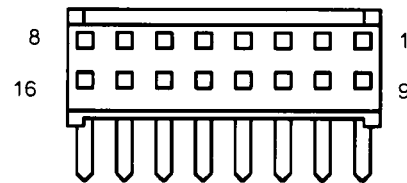
Using 16-pole Berg/Dupont connector

| Pin 16pol Berg/Dupont- connector | Colour | Signal | Explanation |
|--|--------------|--------|-----------------------------|
| 1 | blue | GND | Ground |
| 2 | white/green | R | Commutation signal |
| 3 | white/yellow | S | Commutation signal |
| 4 | white/grey | T | Commutation signal |
| 5 | violet | K0 | Reference signal |
| 6 | pink | K2 | Incremental signal |
| 7 | white | K1 | Incremental signal |
| 8 | --- | N. C. | |
| 9 | red | Us | Supply voltage 5 V ± 10% |
| 10 | white/pink | R | Inverted commutation signal |
| 11 | white/blue | S | Inverted commutation signal |
| 12 | white/red | T | Inverted commutation signal |
| 13 | yellow | K0 | Inverted reference signal |
| 14 | black | K2 | Inverted incremental signal |
| 15 | brown | K1 | Inverted incremental signal |
| 16 | --- | N. C. | |

Please note! Pins which are designated by „N. C.“ must not be connected.

View on plug side

ST1



Notice! The encoder housing must be connected to the screen. The 200 mm long screen wire attached to the encoder is designed for this purpose.

Stranded cable

Item number
046 029 000 330

The stranded cable with Berg-Dubox-connection 2 x 8 is not included in the scope of delivery. Please order separately.

